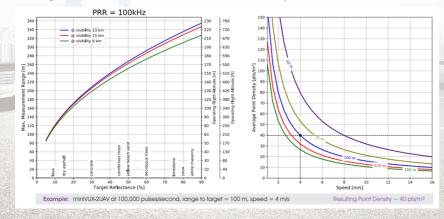
# **Specification**

LiDAR System	
Laser Range	max. 330 m
Field of View	0°~ 360°
Angle Resolution	0.001°
Max. Meas. Rate	up to 200,000 meas./sec
Accuracy	H/V: 5 cm @50 m; H/V: 10 cm@100 m (UAV)
	H/V: 3 cm (Automotive)
Camera	24.3 MP RGB
Recommended scanning height AGL	10-160 m
Weight	2.5 kg (w/o camera)
Dimensions	307 x 94 x 116 mm
Input Voltage	11-30V DC
Power Consumption	27 W
Part I: Laser Scanner	
Type	RIEGL miniVUX-2UAV
Wavelength	1550 nm
Eye Safety Class	laser class 1
Laser Pluse Repetition Rate	100 kHz / 200 kHz selectable
Scan Speed	10-100 scans/sec
Multi-echo effect	up to 5 echoes per shot
Accuracy / Precision	15 mm / 10 mm
Data Storage	SDHC/SDXC 32 GB ( 128 GB max.)
Environment Protection	IP64
Temperature	operating: -10° to 40°C; storage: -20° to 50°C
Part II: POS System	
Туре	STIM300
Gyro Bias Instability	0.5°per hour
Gyroscope input range	400 deg/sec
Accelerometer Range	±10 g
Processed Roll/Pitch Accuracy	0.006°
Processed Heading Accuracy	0.019°
Processed location H/V Accuracy	0.01/0.02 m
Processed Speed H/V Accuracy	0.02/0.01 (m/s)
Data Sampling Rate	POS: 125 Hz; Location: 5 Hz
Internal Memory	16 GB

## **Package**

Itama	Recommended Configuration		
Item	UAV-based	SUV-based	
	hard	ware	
LiDAR Sensor	SZT-R250II	SZT-R250II	
Imaging Sensor	Sony ILCE-a6000	FLIR LadyBug5+	
Carrier Platform	DJI Matrice600 Pro	(conventional SUV models)	

# **Target Reflectance & Point Density**





SOUTH SURVEYING & MAPPING TECHNOLOGY CO., LTD.

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impexp@southsurvey.com euoffice@southsurvey.com

http://www.southinstrument.com







# Several days or just a single day? **LiDAR chooses for you!**



fliabe aleienda	maint danait.	estimated coverage	
flight altitude	point density	per flight	per day
50 m	86-130 pts/sq.m	0.25 sq.km (25 ha)	2.5 sq.km (250 ha)
75 m	58-86 pts/sq.m	0.40 sq.km (40 ha)	4 sq.km (400 ha)
100 m	44-64 pts/sq.m	0.90 sq.km (90 ha)	9 sq.km (900 ha)
125 m	34-52 pts/sq.m	1.20 sq.km (120 ha)	12 sq.km (1200 ha)
150 m	32-48 pts/sq.m	1.40 sq.km (140 ha)	14 sq.km (1400 ha)

Note: the data shown above is based on flat terrain conditions for job reference only, and the estimated coverage per day is computed with 10 flights in total. Complex terrain of elevated areas or vegetated zones might reduce the work efficiency somehow. With the same laser emitting power, the point density varies greatly from reflective distance and reflective ratio of the target, moving speed of the carrier and air permeability. Theoretically, higher point density is possible with customized flight plans while bigger coverage figures are expectable with increased flight numbers.

	. , ,		roadway to scan per day	
7	scanning speed	line spacing	1-3 lanes	4-6 lanes
	18 km/h	5 cm	108 km	54 km
9	36 km/h	10 cm	216 km	108 km
	54 km/h	15 cm	324 km	162 km
	72 km/h	20 cm	432 km	216 km

Note: the line spacing figures were computed by driving speeds and mileage efficiency was generated from 6-hour effective mobile scanning accordingly. The ground base station is recommended to shift to the next location ahead when the radio datalink radius exceeds 25 km. In case of roads with dense traffic conditions or with green belts/isolation guardrails in the middle of 2-way, it's required to conduct multiple drives for filling the data gaps due to earlier occlusions.



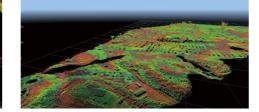
### **Tough Topographic Survey Jobs**

- highly efficient aerial data capture for topographic or cadastral survey
- · excellent elevation accuracy control within centimeter level
- ideal for highly vegetated areas due to canopy
- ready for aerial lasergrammetry in places hard to reach or hard to track GPS signals



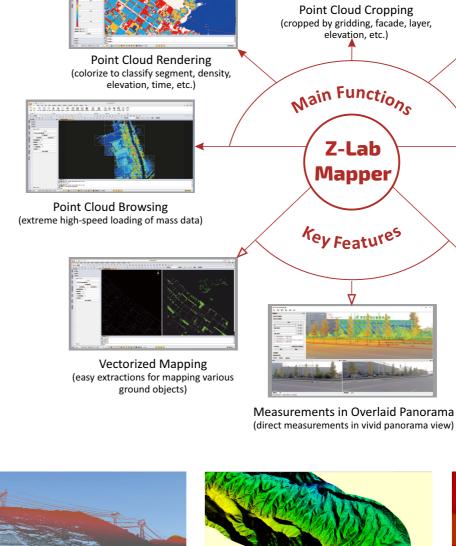
### **Traffic Network Development**

- · highly efficient terrestrial data capture by linear mobile laser scanning
- designed for topographic survey of road/railway system development or expansion
- tailored to asset inventory survey of road/railway system against maintenance and evaluation
- an ideal alternative of total station or RTK survey due to a variety of satisfactory outputs

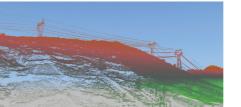


## Forestry Investigation & Planning

- highly efficient aerial data capture for topographic survey in jungles or forests
- to obtain abundant indicative information such as tree height, stem diameter, canopy shape, etc. in short time
- ideal for species identification, deforestation planning & investigation



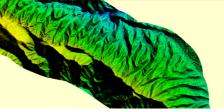
**Inertial Explorer** 



Z-Lab LiDAR-ctrl

## **Applications in Power Transmission Industry**

- · fast and contactless 3D data capture of power lines and ground surface attachments
- to provide visualized and analytical management for existing power lines network
- to identify defects on transmission lines through geo-referenced point cloud
- ideal for digital transfer of survey, design and engineering accomplishments

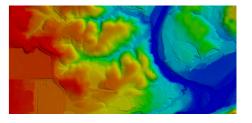


**Software Solution** 

**Z-Lab Pt-process** 

## **Disaster Monitoring & Emergency Response**

- laser scanning is unaffected by light conditions while airborne mode won't suffer from traffic chaos
- to obtain topographic data and terrain features in disaster areas for realtime analysis
- quick reference for disaster relief and post-disaster reconstruction arrangements



3D View in GoogleEarth

(accessible to GoogleEarth for

geo-spatial display)

#### **Irrigation System Development**

**Z-Lab Mapper** 

Point Cloud Accuracy Control

(rectified by control points input

& tie points matching)

**3-dimension Measurements** 

(coordinate, distance, volume, etc.)

**TerraSolid** 

- to conduct topographic survey with data capture of vegetations and ground objects
- to obtain high-precision digital terrain model and orthophoto map for irrigation works planning
- ideal for location optimization, engineering control, landslide monitoring, flow direction analysis, etc.