SPECIFICATIONS

GNSS Features

GNSS Features	Communications
Channels	I/O Port5-PIN LEMO external power port + RS232
GPSL1C/A, L2C, L2P, L5	7-PIN LEMO(USB, OTG and Ethernet)
GLONASSL1C/A,L1P,L2C/A,L2P,L3*	1 PPS data interface
BDS	SIM card slot(standard)
BDS-3: B1I, B3I, B1C, B2a, B2b*	Internal UHF Receiver and transmitter 1/2/3W
GALILEO E1, E5A, E5B, E6C, AltBOC*	(Just receiver 0.01W for Russia)
SBAS(WAAS/MSAS/EGNOS/GAGAN)	Frequency range
IRNSS	Communication protocol
QZSS. L1, L2C, L5*	HUACE, ZHD
MSS L-BandRTX*	Communication rangeTypically 10km with Farlink protocol
	Cellular mobile network
Positioning output rate	Bluetooth
Initialization time	NFC Communication
Initialization reliability> 99.99%	
	automatic pair between receiver and
	controller (controller requires NFC
Positioning Precision	wireless communication module else)
Code differential GNSS Horizontal: 0.25 m + 1 ppm RMS	
Vertical: 0.50 m + 1 ppm RMS	
Static(long observations)Horizontal: 2.5 mm + 0.1 ppm RMS	Data Storage/Transmission
Vertical: 3 mm + 0.4 ppm RMS	Storage
StaticHorizontal: 2.5 mm + 0.5 ppm RMS	Automatic cycle storage (The earliest data
Vertical: 3.5 mm + 0.5 ppm RMS	files will be removed automatically while the
Rapid static Horizontal: 2.5 mm + 0.5 ppm RMS	memory is not enough)
Vertical: 5 mm + 0.5 npm RMS	Support external USB storage
PPKHorizontal: 3 mm + 1 ppm RMS	Data transmissionPlug and play mode of USB data transmission
Vertical: 5 mm + 1 ppm RMS	Supports FTP/HTTP data download
RTK(UHF)Horizontal: 8 mm + 1 ppm RMS	Data formatStatic data format: STH, Rinex2.01, Rinex3.02, etc.
Vertical: 15 mm + 1 ppm RMS	Differential format: CMR(GPS only), CMR+(GPS only),
RTK(NTRIP) Horizontal: 8 mm + 0.5 ppm RMS	
Variable 45 mars + 0.5 mars DMC	RTCM 2.3, RTCM 3.0, RTCM 3.1, RTCM 3.2
Vertical: 15 mm + 0.5 ppm RMS	Navigation data format: NMEA 0183, PJK, Binary code
RTK initialization time	Network model support: VRS, FKP, MAC,
SBAS positioningTypically < 5m 3DRMS	fully support NTRIP protocol
IMULess than 10mm + 0.7 mm/° tilt to 30°	
IMU tilt angle $0^{\circ} \sim 60^{\circ}$	Sensors
	Electronic bubbleController software can display electronic
Hardware Performance	bubble, checking leveling status of the
Dimension	carbon pole in real-time
Weight	IMUBuilt-in IMU module, calibration-free
Magnesium aluminum allov shall	and immune to magnetic interference
Material	Thermometer Built-in thermometer sensor, adopting intelligent
Operating temperature45°C ~ +65°C	temperature control technology, monitoring
Storage temperature45°C ~ +85°C	and adjusting the receiver temperature
Humidity100% Non-condensing	, , ,
Waterproof/DustproofIP68 standard, protected from long	Hear latered to a
time immersion to depth of 1m	User Interaction
IP68 standard, fully protected against	Operating systemLinux
blowing dust	Buttons
Shock/Vibration Withstand 2 meters pole drop onto	Indicators
the cement ground naturally	Web interaction With the access of the internal web interface
Power consumption	management via WiFi or USB connection, users
Power supply 6-28V DC, overvoltage protection	are able to monitor the receiver status and
Battery7.4V 3400mAh x 2 rechargeable,	change the configurations freely
	Voice guidance
removable Li-ion battery Battery life(Dual-battery)¹15h(Rover Bluetooth mode)	and supports Chinese/English/
Dattery includar-pattery)15n(Kover Bluetooth mode)	Korean/Spanish/Portuguese/Russian/Turkish
WIFI	Secondary development
	kit, and opens the OpenSIC observation
Modem	data format and interaction interface definition
WIFI hotspotAP mode, Receiver broadcasts its hotspot form web UI	Cloud serviceThe powerful cloud platform provides online
accessing with any mobile terminals	
WIFI datalink Client mode, Receiver can transmit and receive correction	services like remote manage, firmware update,
data stream via WiFi datalink	online register and etc.

Communications

Items marked with * will be upgraded along with the update of assigned firmware version

The data comes from the SOUTH GNSS Product Laboratory, and the specific situation is subject to local actual usage. The measurement accuracy, precision and reliability are associated to various factors, including number of satellite tracking, observation time, multi-path, etc.

1.Actual battery life can vary depending on usage patterns and other factors. The listed parameter was obtained under controlled testing conditions.





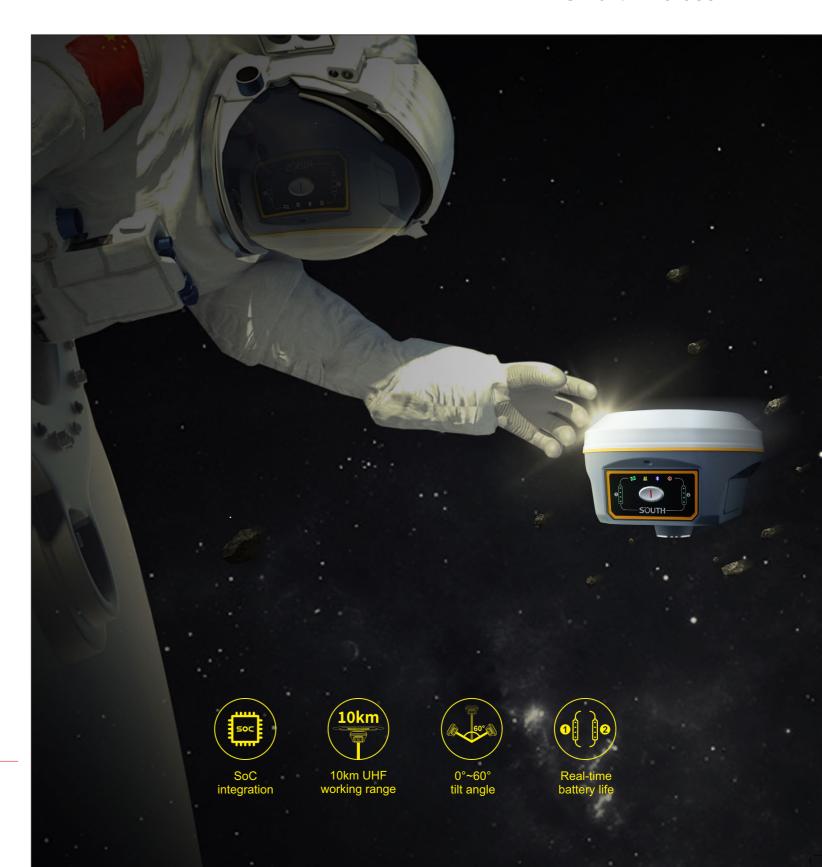
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G9

— Smart wireless RTK —



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High integration creates convenient field work

Carrying a new RTK integration technology, Bluetooth, WIFI, GSM antennas are highly integrated into GNSS antenna, that brings you an unprecedented experience of field surveying, making the field work more convenient and easier.

Intelligent Base signal locking technology

Using one-to-one signal tracking and locking technology, and the independent frequency under Farlink protocol, the G9 rover can continuously lock and capture the target base station signal to reduce cross-frequency interference even though other base stations are working nearby with the same channel.



The ultimate internal UHF performance

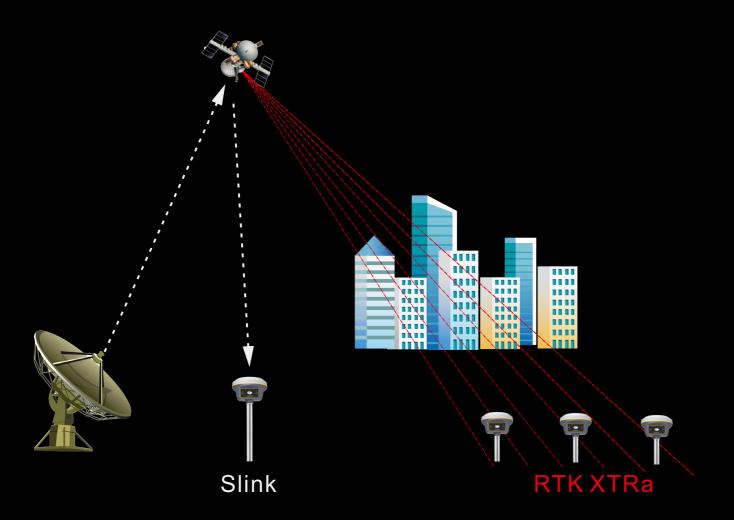
The G9 breaks through the constraints on wavelengths based on a SOUTH high-performance UHF module with Farlink communication technology, which increases signal sensitivity and transmission efficiency, and really achieves the goal of 10km ultra-long-distance working range.



Slink & RTK XTRa

Base on the RTX global services, G9 is able to achieve the goal of precise single-point positioning without a reference, the positioning is no more constrained by terrain environment, such as mountain, wasteland, desert, island, fixed solution is generally available as long as the GNSS constellations are visible.

Moreover, RTK XTRa technology which is derived from RTX services, it can extend RTK positioning for several minutes while the RTK primary source of correction stream is interrupted or not available, it really makes RTK bright anywhere.



Powerful system management —Smart ROS

G9 is integrated with the ROS system, which comes with intelligent deployment of multi-mode hardware components, strong computing power and an intelligent scheduling mechanism, and coupling with an ultra-fine memory management mechanism, making the fluency and running speed of the receiver comprehensively improved.



Efficient and reliable tilt measurement

Built-in high-performance IMU automatic compensator corrects the coordinates to the pole tip, assisting users to quickly and accurately measure or stake out points at will without strict leveling the receiver. The tilt angle range can achieve up to 60°.

Furthermore, the compensation is still available even though the fixed solution is lost for a short time. Users can continue the survey after the fixed solution recovers without initializing the IMU module again, which helps surveyors boost productivity by 30 percent.











Super long working hours

G9 also adopts a dual-battery system design so that it can achieve longer battery life while maintaining strong performance. The hot replaceable function allows you to change the battery one by one when power is low. You can continue with work without switching off the receiver.

The G9 receiver is able to continuously work for about 15 hours in Rover+Bluetooth mode with 2 batteries. Power volume is visible synchronously on the control panel.

