









Specification

Series Model

Laser Scanner Measurement Rate Laser Safety Class Laser Wavelength Echo Mode Measuring Range Scanning Rate Scanning FOV Horizontal Angle Resolution Vertical Angle Resolution Range Noise Relative Accuracy GNSS Differential[®] Signal Tracking@ RTK Positioning Accuracy² CORS Access² Positioning Data Refresh Rate⁽²⁾ Absolute Accuracy⁽²⁾ Scanning Principle Accumulated Mileage Error Housing Material Weight Dimension System Consumption **Power Supply** Battery Unit Endurance **IP** Protection Temperature **Device Connection** Data Storage Data Download Panoramic Camera Software Package Processing Method Process Time

Robot SLAM RobotSLAM basic, RobotSLAM standard, RobotSLAM professional, RobotSLAM Plus standard, RobotSLAM Plus professional 16-channel^① Max. 320,000 points/sec^① Class 1(IEC 60825-1:2014) eye-safe 905 nm 8-bit, dual return 0.05-120 m 10 Hz 360°x 285° 0.18° (10 Hz) ±2mm to ±4mm for measuring distance below 25m and target reflection above 78% best up to 1 cm GPS+Glonass+Beidou+Galileo multi-constellation tracking 555 channels RMS 1 cm+1 ppm nano SIM card slot built in max. 100 Hz best up to 3-5 cm laser sensor 360° mechanical rotation 0.1%-0.2% (under the condition without loop closure) aviation-grade aluminum, with high protection level and anti-inference capability 1.5 kg (handheld only) 262x230x146 mm 20 w

single battery hours, dual batteries hours IP 64 -20~65°C (operating), -40~85°C (storage) Wi-Fi or Ethernet cable

post-processing on PC approx. 1-2 times of data acquisition

Note:

① to expect higher point rate like 640,000 points/sec max., 32-channel laser sensor is also available upon request, and that's RobotSLAM Plus series. ② GNSS differential performance is only applicable to the standard and professional versions. In outdoor scenes with moderate satellite signals coverage, it is recommended to activate GNSS RTK for positioning, which may help much to eliminate control points record and measurement.

Options

Model	RobotSLAM basic	RobotSLAM standard	RobotSLAM professional
Handheld Components	\checkmark	\checkmark	\checkmark
Control Point Record Button	\checkmark	\checkmark	\checkmark
Built-in GNSS Module		\checkmark	\checkmark
GNSS Antenna		\checkmark	\checkmark
LED Screen	\checkmark	\checkmark	\checkmark
Smartphone Holder	\checkmark	\checkmark	\checkmark
Smartphone APP	\checkmark	\checkmark	\checkmark
Pano Camera	option	option	option
Fill-in Light ^①	option	option	option
Backpack Kit			$\sqrt{2}$
Al Robot Dog Mount Kit ³		option	option
USV-based Mount Kit ^③		option	option
SUV-based Mount Kit ^③		option	option
UAV-based Mount Kit ^③	-	option	option
ites:			

① fill-in light and 360°pano camera are bundled as a visual module.

2 the backpack kit includes a white plate antenna and a longer GNSS antenna cable; the backpack 3-in-1 magic tactically provides two working modes in one package: handheld and backpack, plus the storage function. No carrying case or trolley suitcase needec

③ Al Robot Dog Mount kit, USV-based Mount kit, SUV-based Mount kit and UAV-based Mount kit are all optional accessories, available upon request.

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dual external Li-ion battery, hot swappable DC 14.4V, 6875mAh, 99 Wh (old model); DC 14.4V, 6900mAh, 99 Wh (new model)

built-in SSD, 512GB (extendable upon request); SD card (removable), 128GB via Ethernet cable, WiFi or SD card 2-lens, fisheye, 360°, image pixels 18 MP, video pixels 5.7k RobotSLAM Palm (smartphone APP), RobotSLAM Engine (PC)

dealer info

robol SLAM

A Survey-grade SLAM Handheld

direct geo-referencing amazing cm-level accuracy backpack 3-in-1 magic abundant software functions

(V. 202305)

Illustration



APP&Software **LOEO2** I AM≸ ROSOT SLAM

• task timer

processing replay

Computer Configuration

Requirement	Minimum	Recommended			
OS	Windows10/Windows11 64-bit				
Graphics Card	GTX-3060/RX6600M or above (NVIDIA series recommended)				
CPU	Intel i7-11800H/AMD R7-5800H or above	Intel i7-12700H/AMD R7-6800H or above			
Internal Memory	16GB or above	32GB or above			
SSD	1TB or above	2TB or above			

Note: for faster data loading, it's recommended to process the data directly with SSD instead of HDD.







no pulling on the ground \rightarrow

when 3 becomes 1

① storage packing ② handheld mode

③ backpack mode

Smartphone APP-RobotSLAM Palm

- CORS settings status display
 - fieldwork control
 - storage info
- device registration

Post Processing Software-RobotSLAM Engine

- coordinate system transformation
- auto/manual optimization
- instant loading of mass data
- H.&V. accuracy verification
- loop closure review
- enable RTK for adjustment
- point cloud classification

- point rendering
- 3D measurement
- pano overlay display
- global registration
- auto denoising
- sectional view
- X-ray rendering

held (handle, base plate)	1	B GNSS antenna & cable	1	
tphone holder	1	b shoulder strap	1	
cable	1	battery compartment	1	
rgeable battery	2	\rm battery charger & cable	1	
net cable	1	USB flash drive	1	
SD card	1	SD card reader	1	
ing cloth	1	N hand-carry case	1	
camera (option)	1	P fill-in light & charging cable	1	

Note: the above is applicable for RobotSLAM standard only. Please refer to the configuration list for more details of different models.

















Basement Parking Digitization





Forestry Investigation





		6	6	0			6	24
	TreeID	TreeLocationX	TreeLocationY	TreeHeight	CrownDiameter	CrownArea	CrownVolume	OldiD
2		-48.308	30.817	2.898	0.741	0.431	0.431	4
3	2	+48.839	37,495	2.959	2.967	6.454	6.454	35
4	3	-62.956	31.279	2.154	0.113	0.01	0	50
5	4	9.28	40.994	8.616	4.363	14.948	45.487	23
6	5	4.265	40.901	5.976	2.657	5.543	8.107	
7	6	10.841	52.502	10.155	4.775	17.911	5.47	3
8	7	-53.843	34.695	2.718	0.592	0.275	0.272	38
9	8	2.154	44,502	5.223	4.066	12.984	26.059	15
10	9	20.472	49.049	2.423	0.501	0.197	0.159	
u	10	57.937	38.535	2,468	0.795	0.496	0.496	31
12	11	-31.166	30.015			. 0	0	51
	12	-39	21.69	3.596		0.1	0.076	
14	13	-16.154	21.18					
15	14	-58.157	39.141			0.827		
16	15		29.598	2.531	0.304	0.073	0.073	
17	16	-58.251	28.034	3.61	0.457	0.164	0.131	67
18	17	-21.5	27,668			5.336		
19	18	-47.382						16
20	19	-51.534	39.086	2.923	1.787	2.509	2,509	
a	20					8.067		
22	21	.258	29.247	5.9	3.07	7.4	18 747	61

Stockpile Volume Calculation



Shoreside Survey + USV Bathymetry





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